

# TROUBLESHOOTING

POWERFLEX 525

# Manual Parameter Tuning

There are four main parameters on the PowerFlex 525 that will solve most startup or performance issues.

- · Parameter A531 Start Boost (0-25%)
- Parameter A532 Break Voltage (0-100%)
- · Parameter P041 Acceleration Time (Seconds)
- · Parameter P042 Deceleration Time (Seconds)

#### Here are important parameters to monitor.

- · Parameter B003 (Output Current) Real time amperage draw of motor.
- Parameter P034 (P/N FLA) Full Load Amperage of motor.

#### There are four protection parameters that should NEVER be modified

- · Parameter A486 Shear Pin 1 Level (Max Safe Amperage)
- · Parameter A487 Shear Pin 1 Time (Over FLA for 10 Seconds)
- · Parameter A488 Shear Pin 2 Level (Overload Current)
- · Parameter A489 Shear Pin 2 Time (Above OL for 3 Seconds)

Always start tuning with A531, A532 should be tuned if motor "pulses" or "oscillates".

Before tuning verify there are no mechanical interference or binding issues.



## Torque Boost Tuning (Parameter A531 – Start Boost)

#### You will need:

- · P/N Technical Details Sheet
- · P/N FLA Value

### **Tuning Instructions:**

- 1. Set Starting Value to 7% (Rarely is this value below 6% or above 9%)
- 2. Set Speed to OHz. Commanded frequency for tuning.
- 3. Start motor & Monitor Parameter B003 (Output Current of drive)
- 4. Adjust parameter A531 up or down by values of 1 until B003 (Output Current of drive) is equal to 60% of parameter P034 (P/N FLA)

(Example: Your FLA is 2.2 Amps, so 2.2A \* .6 = 1.32A. So, you want your B003 to be around 1.3 amps)

Once these parameters are dialed in, rerun Power On / Start Up procedures.

If performance issues persist, move on to Break Voltage Tuning.

# Break Voltage Tuning (Parameter A532 – Break Voltage)

#### You will need:

· P/N Technical Details Sheet

Note: You only need to adjust this parameter if the motor doesn't operate correctly, after you have changed the A531 parameter.

#### **Tuning Instructions:**

- 1. Set parameter A532 to 30% Starting Value (rarely is this value below 20% or above 50%)
- 2. If the drive trips from over current, this value can be decreased by 5%
- 3. If the motor doesn't start/run in a constant forward motion, increase this by 5%

Changing break voltage settings usually wont increase current, In some cases it does, and may cause issues. Proceed with caution.



### Acceleration Time (Parameter P041)

In the event of oscillation or pulsing you may want to increase this to a longer ramp up time in seconds. This is dependent on your application's requirements. (This value is measured in seconds)

# Deceleration Time (Parameter P042)

In some situations you may want to adjust deceleration time to allow for application needs. This is dependent on your application's requirements. (This value is measured in seconds)

Param	Name	Alterability	Description
31	Motor NP Volts	Drive Specific	Drive determines this value
32	Motor NP Hertz	Motor Specific	60 Hz - Rated Frequency
33	Motor OL Current	Motor Specific	Peak Current/Maximum Current
34	Motor NP FLA	Motor Specific	Full Load Current - Max amps continuous run @
35	Motor NP Poles	Motor Specific	Number of motor poles
36	MOTOR NP RPM	Motor Specific	RPM of motor. Determined by # of poles & freq.
37	Motor NP Power	Motor Specific	Power(watts) = Volts * Amps
9*	PM Mode	Every Motor!	Permanent magnet mode setting on drive!!
41	Accel Time 1	Customer specific	Longer accel time = less current needed
42	Decel Time 1	Customer specific	Longer decel time = less current needed
186*	Shear Pin1 Lvl	Motor Specific!	Above FLA but below OL amps for P487 sec.
487	Shear Pin 1 Time	Permenant Magnet Setting	Determines cutoff seconds for P486
488	Shear Pin2 Level	Permenant Magnet Setting	Over OL current for P489 seconds
489	Shear Pin 2 Time	Permenant Magnet Setting	Determines cutoff seconds for P488
501	PM IR Voltage	Motor Specific	Voltage across the stator resistance
502	PM IXd Voltage	Motor Specific	Voltage across the d-axis stator inductance
503	PM IXq Voltage	Motor Specific	Voltage across the q-axis stator inductance
504	PM BEMF Voltage	Motor Specific	Back electromotive force (generator effect)
517	PM DC Inject Cur	Permenant Magnet Setting	Max DC current to reset stator position
518	PM Align Time	Permenant Magnet Setting	Magnetic pole reorientation time
527	PM FWKn 1 Kp	Permenant Magnet Setting	gain for performance in field weakening region
528	PM FWKn 2 Kp	Permenant Magnet Setting	gain for robustness step load weakening region
530	Boost Select	Permenant Magnet Setting	Sets A531 (% of P031[NP Volts]) & V/Hz curve
531	Start Boost	Customer specific	Sets boost Volts(% of P031 NP Volts)
532	Break Voltage	Customer specific	Sets voltage (in % of base freq) @ A533
533	Break Frequency	Advanced customer specific	Sets freq where A532(Break Voltage) is applied
580	Current Loop BW	Permenant Magnet Setting	Current feedback loop
583	PM Stable 1 Kp	Permenant Magnet Setting	% of gain for stabilization loop
584	PM Stable 2 Kp	Permenant Magnet Setting	Gain for stabilization loop
585	PM Stable 8rk Pt	Permenant Magnet Setting	% of P037 NP Power for gain of A584
586	PM Stepload Kp	Permenant Magnet Setting	gain for robustness under step load @ low speed
587	PM 1 Efficiency	Advanced customer specific	Efficiency control when motor is loaded
588	PM 2 Efficiency	Advanced customer specific	Efficiency control when motor is not loaded

This is a breakdown of parameter functions.

Green - Safe to Modify

Yellow - Use Caution

Red, Blue & Orange - Do Not Modify

### Contact Information

### For advanced support:

om.support@actionpaq.com